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**waveline**

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# LIBRARY DOCUMENTATION

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Library to easily interface with Vallen Systeme WaveLine™ devices using the public APIs.

<code>waveline.spotwave</code>	Module for spotWave device.
<code>waveline.linwave</code>	Module for linWave device.
<code>waveline.conditionwave</code>	Module for conditionWave device (alias for <code>waveline.linwave</code> , <i>deprecated</i> ).
<code>waveline.datatypes</code>	Common datatypes.
<code>waveline.utils</code>	Utility functions.



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# CHAPTER ONE

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## WAVELINE.SPOTWAVE

Module for spotWave device.

All device-related functions are exposed by the *SpotWave* class.

### Classes

<i>Info</i> (firmware_version, type_, model, input_range)	Device information.
<i>Setup</i> (recording, logging, cont_enabled, ...)	Setup.
<i>SpotWave</i> (port)	Interface for spotWave devices.
<i>Status</i> (temperature, recording, logging, ...)	Status information.

### 1.1 Info

```
class waveline.spotwave.Info(firmware_version, type_, model, input_range)
    Device information.

    __init__(firmware_version, type_, model, input_range)
```

#### Methods

```
__init__(firmware_version, type_, model, ...)
```

#### Attributes

<i>firmware_version</i>	Firmware version (major, minor)
<i>type_</i>	Device type
<i>model</i>	Model identifier
<i>input_range</i>	Input range

```
firmware_version: str
    Firmware version (major, minor)
```

```
type_: str  
    Device type  
model: str  
    Model identifier  
input_range: str  
    Input range
```

## 1.2 Setup

```
class waveline.spotwave.Setup(recording, logging, cont_enabled, adc_to_volts, threshold_volts, ddt_seconds,  
                               status_interval_seconds, filter_highpass_hz, filter_lowpass_hz, filter_order,  
                               tr_enabled, tr_decimation, tr_pretrigger_samples, tr_postduration_samples)  
  
Setup.  
  
__init__(recording, logging, cont_enabled, adc_to_volts, threshold_volts, ddt_seconds,  
        status_interval_seconds, filter_highpass_hz, filter_lowpass_hz, filter_order, tr_enabled,  
        tr_decimation, tr_pretrigger_samples, tr_postduration_samples)
```

### Methods

```
__init__(recording, logging, cont_enabled, ...)
```

### Attributes

recording	Flag if acquisition is active
logging	Flag if logging is active
cont_enabled	Flag if continuous mode is enabled
adc_to_volts	Conversion factor from ADC values to volts
threshold_volts	Threshold for hit-based acquisition in volts
ddt_seconds	Duration discrimination time (DDT) in seconds
status_interval_seconds	Status interval in seconds
filter_highpass_hz	Highpass frequency in Hz
filter_lowpass_hz	Lowpass frequency in Hz
filter_order	Filter order
tr_enabled	Flag in transient data recording is enabled
tr_decimation	Decimation factor for transient data
tr_pretrigger_samples	Pre-trigger samples for transient data
tr_postduration_samples	Post-duration samples for transient data

```
recording: bool  
    Flag if acquisition is active  
logging: bool  
    Flag if logging is active
```

---

```

cont_enabled: bool
    Flag if continuous mode is enabled

adc_to_volts: float
    Conversion factor from ADC values to volts

threshold_volts: float
    Threshold for hit-based acquisition in volts

ddt_seconds: float
    Duration discrimination time (DDT) in seconds

status_interval_seconds: float
    Status interval in seconds

filter_highpass_hz: Optional[float]
    Highpass frequency in Hz

filter_lowpass_hz: Optional[float]
    Lowpass frequency in Hz

filter_order: int
    Filter order

tr_enabled: bool
    Flag in transient data recording is enabled

tr_decimation: int
    Decimation factor for transient data

tr_prettrigger_samples: int
    Pre-trigger samples for transient data

tr_postduration_samples: int
    Post-duration samples for transient data

```

## 1.3 SpotWave

```
class waveline.spotwave.SpotWave(port)
```

Interface for spotWave devices.

The spotWave device is connected via USB and exposes a virtual serial port for communication.

**\_\_init\_\_(port)**

Initialize device.

**Parameters**

**port** (`Union[str, Serial]`) – Either the serial port id (e.g. “COM6”) or a `serial.Serial` port instance. Use the method `discover` to get a list of ports with connected spotWave devices.

**Returns**

Instance of `SpotWave`

## Example

There are two ways constructing and using the *SpotWave* class:

1. Without context manager and manually calling the *close* method afterwards:

```
>>> sw = waveline.SpotWave("COM6")
>>> print(sw.get_setup())
>>> ...
>>> sw.close()
```

2. Using the context manager:

```
>>> with waveline.SpotWave("COM6") as sw:
>>>     print(sw.get_setup())
>>>     ...
```

## Methods

<code>__init__(port)</code>	Initialize device.
<code>acquire([raw, poll_interval_seconds])</code>	High-level method to continuously acquire data.
<code>clear_buffer()</code>	Clear input and output buffer.
<code>clear_data_log()</code>	Clear logged data from internal memory.
<code>close()</code>	Close serial connection to the device.
<code>connect()</code>	Open serial connection to the device.
<code>discover()</code>	Discover connected spotWave devices.
<code>get_ae_data()</code>	Get AE data records.
<code>get_data(samples[, raw])</code>	Read snapshot of transient data with maximum sampling rate (2 MHz).
<code>get_data_log()</code>	Get logged AE data records data from internal memory
<code>get_info()</code>	Get device information.
<code>get_setup()</code>	Get setup.
<code>get_status()</code>	Get status.
<code>get_tr_data([raw])</code>	Get transient data records.
<code>identify()</code>	Blink LED to identify device.
<code>set_cct(interval_seconds[, sync])</code>	Set coupling check transmitter (CCT) / pulser interval.
<code>set_continuous_mode(enabled)</code>	Enable/disable continuous mode.
<code>set_datetime([timestamp])</code>	Set current date and time.
<code>set_ddt(microseconds)</code>	Set duration discrimination time (DDT).
<code>set_filter([highpass, lowpass, order])</code>	Set IIR filter frequencies and order.
<code>set_logging_mode(enabled)</code>	Enable/disable data log mode.
<code>set_status_interval(seconds)</code>	Set status interval.
<code>set_threshold(microvolt)</code>	Set threshold for hit-based acquisition.
<code>set_tr_decimation(factor)</code>	Set decimation factor of transient data.
<code>set_tr_enabled(enabled)</code>	Enable/disable recording of transient data.
<code>set_tr_postduration(samples)</code>	Set post-duration samples for transient data.
<code>set_tr_pretrigger(samples)</code>	Set pre-trigger samples for transient data.
<code>start_acquisition()</code>	Start acquisition.
<code>stop_acquisition()</code>	Stop acquisition.
<code>stream(*args, **kwargs)</code>	Alias for <i>SpotWave.acquire</i> method.

## Attributes

<code>CLOCK</code>	Internal clock in Hz
<code>PRODUCT_ID</code>	USB product id of SpotWave device
<code>VENDOR_ID</code>	USB vendor id of Vallen Systeme GmbH
<code>connected</code>	Check if the connection to the device is open.

**VENDOR\_ID = 8849**

USB vendor id of Vallen Systeme GmbH

**PRODUCT\_ID = 272**

USB product id of SpotWave device

**CLOCK = 2000000**

Internal clock in Hz

**connect()**

Open serial connection to the device.

The `connect` method is automatically called in the constructor. You only need to call the method to reopen the connection after calling `close`.

**close()**

Close serial connection to the device.

**property connected: bool**

Check if the connection to the device is open.

**classmethod discover()**

Discover connected spotWave devices.

**Return type**

`List[str]`

**Returns**

List of port names

**identify()**

Blink LED to identify device.

---

**Note:** Available since firmware version 00.2D.

---

**clear\_buffer()**

Clear input and output buffer.

**get\_info()**

Get device information.

**Return type**

`Info`

**Returns**

Dataclass with device information

**get\_setup()**

Get setup.

**Return type**

*Setup*

**Returns**

Dataclass with setup information

**get\_status()**

Get status.

**Return type**

*Status*

**Returns**

Dataclass with status information

**set\_continuous\_mode(*enabled*)**

Enable/disable continuous mode.

Threshold will be ignored in continuous mode. The length of the records is determined by *ddt* with *set\_ddt*.

---

**Note:** The parameters for continuous mode with transient recording enabled (*set\_tr\_enabled*) have to be chosen with care - mainly the decimation factor (*set\_tr\_decimation*) and *ddt* (*set\_ddt*). The internal buffer of the device can store up to ~200.000 samples.

If the buffer is full, data records are lost. Small latencies in data polling can cause overflows and therefore data loss. One record should not exceed half the buffer size (~100.000 samples). 25% of the buffer size (~50.000 samples) is a good starting point. The number of samples in a record is determined by *ddt* and the decimation factor *d*:  $n = ddt_{\mu s} \cdot f_s/d = ddt_{\mu s} \cdot 2/d \implies ddt_{\mu s} \approx 50.000 \cdot d/2$

On the other hand, if the number of samples is small, more hits are generated and the CPU load increases.

---

**Parameters**

**enabled** (`bool`) – Set to *True* to enable continuous mode

**set\_ddt(*microseconds*)**

Set duration discrimination time (DDT).

**Parameters**

**microseconds** (`int`) – DDT in  $\mu$ s

**set\_status\_interval(*seconds*)**

Set status interval.

**Parameters**

**seconds** (`int`) – Status interval in s

**set\_tr\_enabled(*enabled*)**

Enable/disable recording of transient data.

**Parameters**

**enabled** (`bool`) – Set to *True* to enable transient data

**set\_tr\_decimation(*factor*)**

Set decimation factor of transient data.

The sampling rate of transient data will be 2 MHz / *factor*.

---

**Parameters**

**factor** (`int`) – Decimation factor

**set\_tr\_pretrigger(samples)**

Set pre-trigger samples for transient data.

**Parameters**

**samples** (`int`) – Pre-trigger samples

**set\_tr\_postduration(samples)**

Set post-duration samples for transient data.

**Parameters**

**samples** (`int`) – Post-duration samples

**set\_cct(interval\_seconds, sync=False)**

Set coupling check transmitter (CCT) / pulser interval.

The pulser amplitude is 3.3 V.

**Parameters**

- **interval\_seconds** (`int`) – Pulser interval in seconds
- **sync** (`bool`) – Synchronize the pulser with the first sample of the `get_data` command

**set\_filter(highpass=None, lowpass=None, order=4)**

Set IIR filter frequencies and order.

**Parameters**

- **highpass** (`Optional[float]`) – Highpass frequency in Hz (`None` to disable highpass filter)
- **lowpass** (`Optional[float]`) – Lowpass frequency in Hz (`None` to disable lowpass filter)
- **order** (`int`) – Filter order

**set\_datetime(timestamp=None)**

Set current date and time.

**Parameters**

**timestamp** (`Optional[datetime]`) – `datetime.datetime` object, current time if `None`

**set\_threshold(microvolts)**

Set threshold for hit-based acquisition.

**Parameters**

**microvolts** (`float`) – Threshold in  $\mu\text{V}$

**set\_logging\_mode(enabled)**

Enable/disable data log mode.

**Parameters**

**enabled** (`bool`) – Set to `True` to enable logging mode

**start\_acquisition()**

Start acquisition.

**stop\_acquisition()**

Stop acquisition.

**get\_ae\_data()**

Get AE data records.

**Return type**

`List[AERecord]`

**Returns**

List of AE data records (either status or hit data)

**get\_tr\_data(raw=False)**

Get transient data records.

**Parameters**

`raw (bool)` – Return TR amplitudes as ADC values if *True*, skip conversion to volts

**Return type**

`List[TRRecord]`

**Returns**

List of transient data records

**acquire(raw=False, poll\_interval\_seconds=0.01)**

High-level method to continuously acquire data.

**Parameters**

- `raw (bool)` – Return TR amplitudes as ADC values if *True*, skip conversion to volts
- `poll_interval_seconds (float)` – Pause between data polls in seconds

**Yields**

AE and TR data records

**Return type**

`Iterator[Union[AERecord, TRRecord]]`

## Example

```
>>> with waveline.SpotWave("COM6") as sw:  
>>>     # apply settings  
>>>     sw.set_ddt(400)  
>>>     for record in sw.stream():  
>>>         # do something with the data depending on the type  
>>>         if isinstance(record, waveline.AERecord):  
>>>             ...  
>>>         if isinstance(record, waveline.TRRecord):  
>>>             ...
```

**stream(\*args, \*\*kwargs)**

Alias for `SpotWave.acquire` method.

Deprecated: Please us the `acquire` method instead.

**get\_data(samples, raw=False)**

Read snapshot of transient data with maximum sampling rate (2 MHz).

**Parameters**

- `samples (int)` – Number of samples to read

- **raw** (`bool`) – Return ADC values if *True*, skip conversion to volts

**Return type**  
`ndarray`

**Returns**

Array with amplitudes in volts (or ADC values if *raw* is *True*)

**get\_data\_log()**

Get logged AE data records data from internal memory

**Return type**  
`List[AERecord]`

**Returns**

List of AE data records (either status or hit data)

**clear\_data\_log()**

Clear logged data from internal memory.

## 1.4 Status

```
class waveline.spotwave.Status(temperature, recording, logging, log_data_usage, datetime)
```

Status information.

```
__init__(temperature, recording, logging, log_data_usage, datetime)
```

### Methods

```
__init__(temperature, recording, logging, ...)
```

### Attributes

<code>temperature</code>	Device temperature in °C
<code>recording</code>	Flag if acquisition is active
<code>logging</code>	Flag if logging is active
<code>log_data_usage</code>	Log buffer usage in sets
<code>datetime</code>	Device datetime

**temperature: int**

Device temperature in °C

**recording: bool**

Flag if acquisition is active

**logging: bool**

Flag if logging is active

```
log_data_usage: int
    Log buffer usage in sets
datetime: datetime
    Device datetime
```

---

CHAPTER  
TWO

---

## WAVELINE.LINWAVE

Module for linWave device.

All device-related functions are exposed by the *LinWave* class.

### Classes

<i>Info</i> (hardware_id, firmware_version, ...)	Device information.
<i>LinWave</i> (address)	Interface for linWave device.
<i>Setup</i> (adc_range_volts, adc_to_volts, ...)	Setup.
<i>Status</i> (temperature, buffer_size)	Status information.

### 2.1 Info

```
class waveline.linwave.Info(hardware_id, firmware_version, fpga_version, channel_count, input_range,  
    max_sample_rate, adc_to_volts)
```

Device information.

```
__init__(hardware_id, firmware_version, fpga_version, channel_count, input_range, max_sample_rate,  
    adc_to_volts)
```

#### Methods

```
__init__(hardware_id, firmware_version, ...)
```

## Attributes

<code>hardware_id</code>	Unique hardware id (since firmware version 2.13)
<code>firmware_version</code>	Firmware version
<code>fpga_version</code>	FPGA version
<code>channel_count</code>	Number of channels
<code>input_range</code>	List of selectable input ranges
<code>max_sample_rate</code>	Max sampling rate
<code>adc_to_volts</code>	Conversion factors from ADC values to V for both ranges

**`hardware_id: str`**  
Unique hardware id (since firmware version 2.13)

**`firmware_version: str`**  
Firmware version

**`fpga_version: str`**  
FPGA version

**`channel_count: int`**  
Number of channels

**`input_range: List[str]`**  
List of selectable input ranges

**`max_sample_rate: float`**  
Max sampling rate

**`adc_to_volts: List[float]`**  
Conversion factors from ADC values to V for both ranges

## 2.2 LinWave

**`class waveline.linwave.LinWave(address)`**

Interface for linWave device.

The device is controlled via TCP/IP:

- Control port: 5432
- Streaming ports: 5433 for channel 1 and 5434 for channel 2

The interface is asynchronous and using *asyncio* for TCP/IP communication. This is especially beneficial for this kind of streaming applications, where most of the time the app is waiting for more data packets ([read more](#)). Please refer to the examples for implementation details.

**`__init__(address)`**

Initialize device.

### Parameters

**`address (str)`** – IP address of device. Use the method *discover* to get IP addresses of available linWave devices.

### Returns

Instance of *LinWave*

## Example

There are two ways constructing and using the *LinWave* class:

1. Without context manager, manually calling the *connect* and *close* method:

```
>>> async def main():
>>>     lw = waveline.LinWave("192.168.0.100")
>>>     await lw.connect()
>>>     print(await lw.get_info())
>>>     ...
>>>     await lw.close()
>>> asyncio.run(main())
```

2. Using the *async* context manager:

```
>>> async def main():
>>>     async with waveline.LinWave("192.168.0.100") as lw:
>>>         print(await lw.get_info())
>>>         ...
>>> asyncio.run(main())
```

## Methods

<code>__init__(address)</code>	Initialize device.
<code>acquire([raw, poll_interval_seconds])</code>	High-level method to continuously acquire data.
<code>close()</code>	Close connection.
<code>connect()</code>	Connect to device.
<code>discover([timeout])</code>	Discover linWave devices in network.
<code>get_ae_data()</code>	Get AE data records.
<code>get_info()</code>	Get device information.
<code>get_setup(channel)</code>	Get setup information.
<code>get_status()</code>	Get status information.
<code>get_tr_data([raw])</code>	Get transient data records.
<code>get_tr_snapshot(channel, samples[, ...])</code>	Get snapshot of transient data.
<code>identify([channel])</code>	Blink LEDs to identify device or single channel.
<code>set_channel(channel, enabled)</code>	Enable/disable channel.
<code>set_continuous_mode(channel, enabled)</code>	Enable/disable continuous mode.
<code>set_ddt(channel, microseconds)</code>	Set duration discrimination time (DDT).
<code>set_filter(channel[, highpass, lowpass, order])</code>	Set IIR filter frequencies and order.
<code>set_range(channel, range_volts)</code>	Set input range.
<code>set_range_index(channel, range_index)</code>	Set input range by index.
<code>set_status_interval(channel, seconds)</code>	Set status interval.
<code>set_threshold(channel, microvolts)</code>	Set threshold for hit-based acquisition.
<code>set_tr_decimation(channel, factor)</code>	Set decimation factor of transient data and streaming data.
<code>set_tr_enabled(channel, enabled)</code>	Enable/disable recording of transient data.
<code>set_tr_postduration(channel, samples)</code>	Set post-duration samples for transient data.
<code>set_tr_pretrigger(channel, samples)</code>	Set pre-trigger samples for transient data.
<code>start_acquisition()</code>	Start data acquisition.
<code>start_pulsing(channel[, interval, count, cycles])</code>	Start pulsing.
<code>stop_acquisition()</code>	Stop data acquisition.
<code>stop_pulsing()</code>	Start pulsing.
<code>stream(channel, blocksize, *[raw, timeout])</code>	Async generator to stream channel data.

## Attributes

<code>CHANNELS</code>	Available channels
<code>MAX_SAMPLERATE</code>	Maximum sampling rate in Hz
<code>PORT</code>	Control port number
<code>RANGES</code>	
<code>connected</code>	Check if connected to device.

```
CHANNELS = (1, 2)
Available channels

MAX_SAMPLERATE = 10000000
Maximum sampling rate in Hz

PORT = 5432
Control port number
```

---

**classmethod discover(*timeout*=0.5)**

Discover linWave devices in network.

**Parameters**

**timeout** (`float`) – Timeout in seconds

**Return type**

`List[str]`

**Returns**

List of IP addresses

**property connected: bool**

Check if connected to device.

**async connect()**

Connect to device.

**async close()**

Close connection.

**async identify(*channel*=0)**

Blink LEDs to identify device or single channel.

**Parameters**

**channel** (`int`) – Channel number (0 for all to identify device)

---

**Note:** Available since firmware version 2.10.

**async get\_info()**

Get device information.

**Return type**

`Info`

**async get\_status()**

Get status information.

**Return type**

`Status`

**async get\_setup(*channel*)**

Get setup information.

**Parameters**

**channel** (`int`) – Channel number (0 for all channels)

**Return type**

`Setup`

**async set\_range(*channel*, *range\_volts*)**

Set input range.

**Parameters**

- **channel** (`int`) – Channel number (0 for all channels)

- **range\_volts** (`float`) – Input range in volts (0.05, 5)

**async set\_range\_index**(*channel*, *range\_index*)

Set input range by index.

**Parameters**

- **channel** (`int`) – Channel number (0 for all channels)
- **range\_index** (`int`) – Input range index (0: 0.05 V, 1: 5 V)

**async set\_channel**(*channel*, *enabled*)

Enable/disable channel.

**Parameters**

- **channel** (`int`) – Channel number (0 for all channels)
- **enabled** (`bool`) – Set to *True* to enable channel

**async set\_continuous\_mode**(*channel*, *enabled*)

Enable/disable continuous mode.

Threshold will be ignored in continuous mode. The length of the records is determined by *ddt* with *set\_ddt*.

**Parameters**

- **channel** (`int`) – Channel number (0 for all channels)
- **enabled** (`bool`) – Set to *True* to enable continuous mode

**async set\_ddt**(*channel*, *microseconds*)

Set duration discrimination time (DDT).

**Parameters**

- **channel** (`int`) – Channel number (0 for all channels)
- **microseconds** (`int`) – DDT in  $\mu$ s

**async set\_status\_interval**(*channel*, *seconds*)

Set status interval.

**Parameters**

- **channel** (`int`) – Channel number (0 for all channels)
- **seconds** (`int`) – Status interval in s

**async set\_tr\_enabled**(*channel*, *enabled*)

Enable/disable recording of transient data.

**Parameters**

- **channel** (`int`) – Channel number (0 for all channels)
- **enabled** (`bool`) – Set to *True* to enable transient data

**async set\_tr\_decimation**(*channel*, *factor*)

Set decimation factor of transient data and streaming data.

The sampling rate will be 10 MHz / *factor*.

**Parameters**

- **channel** (`int`) – Channel number (0 for all channels)
- **factor** (`int`) – Decimation factor

---

**async set\_tr\_pretrigger(channel, samples)**

Set pre-trigger samples for transient data.

**Parameters**

- **channel** (`int`) – Channel number (0 for all channels)
- **samples** (`int`) – Pre-trigger samples

**async set\_tr\_postduration(channel, samples)**

Set post-duration samples for transient data.

**Parameters**

- **channel** (`int`) – Channel number (0 for all channels)
- **samples** (`int`) – Post-duration samples

**async set\_filter(channel, highpass=None, lowpass=None, order=8)**

Set IIR filter frequencies and order.

**Parameters**

- **channel** (`int`) – Channel number (0 for all channels)
- **highpass** (`Optional[float]`) – Highpass frequency in Hz (*None* to disable highpass filter)
- **lowpass** (`Optional[float]`) – Lowpass frequency in Hz (*None* to disable lowpass filter)
- **order** (`int`) – Filter order

**async set\_threshold(channel, microvolts)**

Set threshold for hit-based acquisition.

**Parameters**

- **channel** (`int`) – Channel number (0 for all channels)
- **microvolts** (`float`) – Threshold in  $\mu\text{V}$

**async start\_acquisition()**

Start data acquisition.

**async stop\_acquisition()**

Stop data acquisition.

**async start\_pulsing(channel, interval=1, count=4, cycles=1)**

Start pulsing.

The number of pulses should be even, because pulses are generated by a square-wave signal (between LOW and HIGH) and the pulse signal should end LOW.

**Parameters**

- **channel** (`int`) – Channel number (0 for all channels)
- **interval** (`float`) – Interval between pulses in seconds
- **count** (`int`) – Number of pulses per channel (should be even), 0 for infinite pulses
- **cycles** (`int`) – Number of pulse cycles (automatically pulse through each channel in cycles). Only useful if all channels are chosen.

**async stop\_pulsing()**

Start pulsing.

Args:

**async get\_ae\_data()**

Get AE data records.

**Return type**

`List[AERecord]`

**Returns**

List of AE data records (either status or hit data)

**async get\_tr\_data(`raw=False`)**

Get transient data records.

**Parameters**

`raw` (`bool`) – Return TR amplitudes as ADC values if *True*, skip conversion to volts

**Return type**

`List[TRRecord]`

**Returns**

List of transient data records

**async get\_tr\_snapshot(`channel`, `samples`, `pretrigger_samples=0`, \*, `raw=False`)**

Get snapshot of transient data.

The recording starts with the execution of the command. The total number of samples is the sum of *samples* and the *pretrigger\_samples*. The trai and time of the returned records are always 0.

**Parameters**

- `channel` (`int`) – Channel number (0 for all channels)
- `samples` (`int`) – Number of samples to read
- `pretrigger_samples` (`int`) – Number of samples to read before the execution of the command
- `raw` (`bool`) – Return TR amplitudes as ADC values if *True*, skip conversion to volts

**Return type**

`List[TRRecord]`

**Returns**

List of transient data records

**async acquire(`raw=False`, `poll_interval_seconds=0.05`)**

High-level method to continuously acquire data.

**Parameters**

- `raw` (`bool`) – Return TR amplitudes as ADC values if *True*, skip conversion to volts
- `poll_interval_seconds` (`float`) – Pause between data polls in seconds

**Yields**

AE and TR data records

**Return type**

`AsyncIterator[Union[AERecord, TRRecord]]`

## Example

```
>>> async with waveline.LinWave("192.254.100.100") as lw:
>>>     # apply settings
>>>     await lw.set_channel(channel=1, enabled=True)
>>>     await lw.set_channel(channel=2, enabled=False)
>>>     await lw.set_range(channel=1, range_volts=0.05)
>>>     async for record in lw.acquire():
>>>         # do something with the data depending on the type
>>>         if isinstance(record, waveline.AERecord):
>>>             ...
>>>         if isinstance(record, waveline.TRRecord):
>>>             ...
>>>             ...
```

**stream**(*channel, blocksize, \*, raw=False, timeout=5*)

Async generator to stream channel data.

### Parameters

- **channel** (`int`) – Channel number [1, 2]
- **blocksize** (`int`) – Number of samples per block
- **raw** (`bool`) – Return ADC values if *True*, skip conversion to volts
- **timeout** (`Optional[float]`) – Timeout in seconds

### Yields

Tuple of

- relative time in seconds (first block: t = 0)
- data as numpy array in volts (or ADC values if *raw* is *True*)

### Raises

`TimeoutError` – If TCP socket read exceeds *timeout*, usually because of buffer overflows

### Return type

`AsyncIterator[Tuple[float, ndarray]]`

## Example

```
>>> async with waveline.LinWave("192.168.0.100") as lw:
>>>     # apply settings
>>>     await lw.set_range(0.05)
>>>     await lw.set_filter(100e3, 500e3, 8)
>>>     # open streaming port before start acq afterwards (order matters!)
>>>     stream = lw.stream(channel=1, blocksize=65536)
>>>     await lw.start_acquisition()
>>>     async for time, block in stream:
>>>         # do something with the data
>>>         ...
>>>         ...
```

## 2.3 Setup

```
class waveline.linwave.Setup(adc_range_volts, adc_to_volts, filter_highpass_hz, filter_lowpass_hz,
                             filter_order, enabled, continuous_mode, threshold_volts, ddt_seconds,
                             status_interval_seconds, tr_enabled, tr_decimation, tr_prettrigger_samples,
                             tr_postduration_samples)

Setup.

__init__(adc_range_volts, adc_to_volts, filter_highpass_hz, filter_lowpass_hz, filter_order, enabled,
        continuous_mode, threshold_volts, ddt_seconds, status_interval_seconds, tr_enabled,
        tr_decimation, tr_prettrigger_samples, tr_postduration_samples)
```

### Methods

```
__init__(adc_range_volts, adc_to_volts, ...)
```

### Attributes

<code>adc_range_volts</code>	ADC input range in volts
<code>adc_to_volts</code>	Conversion factor from ADC values to volts
<code>filter_highpass_hz</code>	Highpass frequency in Hz
<code>filter_lowpass_hz</code>	Lowpass frequency in Hz
<code>filter_order</code>	Filter order
<code>enabled</code>	Flag if channel is enabled
<code>continuous_mode</code>	Flag if continuous mode is enabled
<code>threshold_volts</code>	Threshold for hit-based acquisition in volts
<code>ddt_seconds</code>	Duration discrimination time (DDT) in seconds
<code>status_interval_seconds</code>	Status interval in seconds
<code>tr_enabled</code>	Flag in transient data recording is enabled
<code>tr_decimation</code>	Decimation factor for transient data
<code>tr_prettrigger_samples</code>	Pre-trigger samples for transient data
<code>tr_postduration_samples</code>	Post-duration samples for transient data

`adc_range_volts: float`

ADC input range in volts

`adc_to_volts: float`

Conversion factor from ADC values to volts

`filter_highpass_hz: Optional[float]`

Highpass frequency in Hz

`filter_lowpass_hz: Optional[float]`

Lowpass frequency in Hz

`filter_order: int`

Filter order

---

**enabled:** `bool`  
Flag if channel is enabled

**continuous\_mode:** `bool`  
Flag if continuous mode is enabled

**threshold\_volts:** `float`  
Threshold for hit-based acquisition in volts

**dtt\_seconds:** `float`  
Duration discrimination time (DDT) in seconds

**status\_interval\_seconds:** `float`  
Status interval in seconds

**tr\_enabled:** `bool`  
Flag in transient data recording is enabled

**tr\_decimation:** `int`  
Decimation factor for transient data

**tr\_prettrigger\_samples:** `int`  
Pre-trigger samples for transient data

**tr\_postduration\_samples:** `int`  
Post-duration samples for transient data

## 2.4 Status

```
class waveline.linwave.Status(temperature, buffer_size)
    Status information.

    __init__(temperature, buffer_size)
```

### Methods

<code>__init__(temperature, buffer_size)</code>
---

### Attributes

<code>temperature</code>	Device temperature in °C
<code>buffer_size</code>	Buffer size in bytes

**temperature:** `float`  
Device temperature in °C

**buffer\_size:** `int`  
Buffer size in bytes



## WAVELINE.CONDITIONWAVE

Module for conditionWave device (alias for `waveline.linwave`, *deprecated*).

All device-related functions are exposed by the `ConditionWave` class.

### Classes

<code>ConditionWave(*args, **kwargs)</code>	Interface for conditionWave device.
---	-------------------------------------

### 3.1 ConditionWave

`class waveline.conditionwave.ConditionWave(*args, **kwargs)`

Interface for conditionWave device.

#### Deprecated:

Please use LinWave class instead. The `ConditionWave` class will be removed in the future.

`__init__(*args, **kwargs)`

Initialize device.

#### Parameters

`address` – IP address of device. Use the method `discover` to get IP addresses of available linWave devices.

#### Returns

Instance of LinWave

### Example

There are two ways constructing and using the LinWave class:

- Without context manager, manually calling the `connect` and `close` method:

```
>>> async def main():
>>>     lw = waveline.LinWave("192.168.0.100")
>>>     await lw.connect()
>>>     print(await lw.get_info())
>>>     ...
>>>     await lw.close()
>>> asyncio.run(main())
```

2. Using the async context manager:

```
>>> async def main():
>>>     async with waveline.LinWave("192.168.0.100") as lw:
>>>     print(await lw.get_info())
>>>     ...
>>> asyncio.run(main())
```

## Methods

<code><b>__init__</b>(*args, **kwargs)</code>	Initialize device.
<code>acquire([raw, poll_interval_seconds])</code>	High-level method to continuously acquire data.
<code>close()</code>	Close connection.
<code>connect()</code>	Connect to device.
<code>discover([timeout])</code>	Discover linWave devices in network.
<code>get_ae_data()</code>	Get AE data records.
<code>get_info()</code>	Get device information.
<code>get_setup(channel)</code>	Get setup information.
<code>get_status()</code>	Get status information.
<code>get_tr_data([raw])</code>	Get transient data records.
<code>get_tr_snapshot(channel, samples[, ...])</code>	Get snapshot of transient data.
<code>identify([channel])</code>	Blink LEDs to identify device or single channel.
<code>set_channel(channel, enabled)</code>	Enable/disable channel.
<code>set_continuous_mode(channel, enabled)</code>	Enable/disable continuous mode.
<code>set_ddt(channel, microseconds)</code>	Set duration discrimination time (DDT).
<code>set_filter(channel[, highpass, lowpass, order])</code>	Set IIR filter frequencies and order.
<code>set_range(channel, range_volts)</code>	Set input range.
<code>set_range_index(channel, range_index)</code>	Set input range by index.
<code>set_status_interval(channel, seconds)</code>	Set status interval.
<code>set_threshold(channel, microvolts)</code>	Set threshold for hit-based acquisition.
<code>set_tr_decimation(channel, factor)</code>	Set decimation factor of transient data and streaming data.
<code>set_tr_enabled(channel, enabled)</code>	Enable/disable recording of transient data.
<code>set_tr_postduration(channel, samples)</code>	Set post-duration samples for transient data.
<code>set_tr_pretrigger(channel, samples)</code>	Set pre-trigger samples for transient data.
<code>start_acquisition()</code>	Start data acquisition.
<code>start_pulsing(channel[, interval, count, cycles])</code>	Start pulsing.
<code>stop_acquisition()</code>	Stop data acquisition.
<code>stop_pulsing()</code>	Start pulsing.
<code>stream(channel, blocksize, *[, raw, timeout])</code>	Async generator to stream channel data.

## Attributes

<code>CHANNELS</code>	Available channels
<code>MAX_SAMPLERATE</code>	Maximum sampling rate in Hz
<code>PORT</code>	Control port number
<code>RANGES</code>	
<code>connected</code>	Check if connected to device.

---

CHAPTER  
FOUR

---

## WAVELINE.DATATYPES

Common datatypes.

### Classes

<code>AERecord(type_, channel, time, amplitude, ...)</code>	AE data record, either status or hit data.
<code>TRRecord(channel, trai, time, samples, data)</code>	Transient data record.

### 4.1 AERecord

```
class waveline.datatypes.AERecord(type_, channel, time, amplitude, rise_time, duration, counts, energy,
                                    trai, flags)
```

AE data record, either status or hit data.

```
__init__(type_, channel, time, amplitude, rise_time, duration, counts, energy, trai, flags)
```

#### Methods

```
__init__(type_, channel, time, amplitude, ...)
```

#### Attributes

<code>type_</code>	Record type (hit or status data)
<code>channel</code>	Channel number
<code>time</code>	Time in seconds
<code>amplitude</code>	Peak amplitude in volts
<code>rise_time</code>	Rise time in seconds
<code>duration</code>	Duration in seconds
<code>counts</code>	Number of positive threshold crossings
<code>energy</code>	Energy (EN 1330-9) in eu (1e-14 V <sup>2</sup> s)
<code>trai</code>	Transient recorder index (key between <code>AERecord</code> and <code>TRRecord</code> )
<code>flags</code>	Hit flags

```
type_: str
    Record type (hit or status data)

channel: int
    Channel number

time: float
    Time in seconds

amplitude: float
    Peak amplitude in volts

rise_time: float
    Rise time in seconds

duration: float
    Duration in seconds

counts: int
    Number of positive threshold crossings

energy: float
    Energy (EN 1330-9) in eu (1e-14 V2s)

trai: int
    Transient recorder index (key between AERecord and TRRecord)

flags: int
    Hit flags
```

## 4.2 TRRecord

```
class waveline.datatypes.TRRecord(channel, trai, time, samples, data, raw=False)
    Transient data record.

    __init__(channel, trai, time, samples, data, raw=False)
```

### Methods

```
    __init__(channel, trai, time, samples, data)
```

## Attributes

<code>raw</code>	ADC values instead of user values (volts)
<code>channel</code>	Channel number
<code>trai</code>	Transient recorder index (key between <i>AERecord</i> and <i>TRRecord</i> )
<code>time</code>	Time in seconds
<code>samples</code>	Number of samples
<code>data</code>	Array of transient data in volts (or ADC values if <code>raw</code> is <i>True</i> )

**channel: int**

Channel number

**trai: int**

Transient recorder index (key between *AERecord* and *TRRecord*)

**time: float**

Time in seconds

**samples: int**

Number of samples

**data: ndarray**

Array of transient data in volts (or ADC values if `raw` is *True*)

**raw: bool = False**

ADC values instead of user values (volts)



## WAVELINE.UTILS

Utility functions.

### Functions

<code>decibel_to_volts(decibel)</code>	Convert from dB(AE) to volts.
<code>volts_to_decibel(volts)</code>	Convert from volts to dB(AE).

### 5.1 decibel\_to\_volts

`waveline.utils.decibel_to_volts(decibel)`

Convert from dB(AE) to volts.

#### Parameters

`decibel` (`Union[float, ndarray]`) – Input in decibel, scalar or array

#### Return type

`Union[float, ndarray]`

#### Returns

Input value(s) in volts

### 5.2 volts\_to\_decibel

`waveline.utils.volts_to_decibel(volts)`

Convert from volts to dB(AE).

#### Parameters

`volts` (`Union[float, ndarray]`) – Input in volts, scalar or array

#### Return type

`Union[float, ndarray]`

#### Returns

Input value(s) in dB(AE)



---

**CHAPTER  
SIX**

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## **CHANGELOG**

All notable changes to this project will be documented in this file.

The format is based on [Keep a Changelog](#), and this project adheres to [Semantic Versioning](#).

### **6.1 Unreleased**

### **6.2 0.7.1 - 2023-10-18**

#### **6.2.1 Fixed**

- [spotwave] Return device names/paths from `SpotWave.discover` method, e.g. `/dev/ttyACM0` instead of `ttyACM0` on Linux systems

### **6.3 0.7.0 - 2023-10-17**

#### **6.3.1 Added**

- [linwave] `LinWave.set_range_index` method
- [linwave] `LinWave.identify` method to blind all LEDs or single channel to identify device/channel
- [linwave] `LinWave.get_tr_snapshot` method (experimental)
- [linwave] Add `hardware_id` to `get_info` output
- [spotwave] `LinWave.identify` method to blind LED
- Add Python 3.11 and 3.12 to CI pipeline
- Examples:
  - `linwave_pulsing`
  - `linwave_cont_tr`

### 6.3.2 Changed

- [spotwave] Remove cct\_seconds field in get\_setup response Setup
- [spotwave] Make readlines method private
- List input range(s) in get\_info response Info.input\_range (human-readable format)
  - Remove linwave.Info.range\_count field
  - Remove spotwave.Info.input\_range\_decibel field

## 6.4 0.6.0 - 2022-08-01

### 6.4.1 Changed

- [linwave] Timeout parameter for LinWave.stream method (to detect buffer overflows), default: 5 s

### 6.4.2 Fixed

- [linwave] Discovery port binding of client
- [linwave] Reduce CPU load in stream by setting TCP limit/buffer

## 6.5 0.5.0 - 2022-06-21

### 6.5.1 Added

- poll\_interval\_seconds parameter for SpotWave.acquire and ConditionWave.acquire / LinWave.acquire method

### 6.5.2 Changed

- Rename ConditionWave to LinWave (and the corresponding module conditionwave to linwave). The ConditionWave class is still an alias for the LinWave class but deprecated and will be removed in the future

### 6.5.3 Fixed

- [linwave] Fix timeouts for multiline responses (get\_info, get\_status, get\_setup)

## 6.6 0.4.1 - 2022-06-20

### 6.6.1 Fixed

- [linwave] Increase TCP read timeout for `get_ae_data` / `get_tr_data` to prevent timeout errors

## 6.7 0.4.0 - 2022-05-17

### 6.7.1 Added

- [linwave] Add all commands of new firmware (hit-based acquisition, pulsing, ...)
- [linwave] Add example for hit-based acquisition
- Add Python 3.9 and 3.10 to CI pipeline

### 6.7.2 Changed

- [linwave] Rename `set_decimation` method to `set_tr_decimation`
- [linwave] Remove `get_temperature` and `get_buffersize` method (replace with `get_status` method)
- [spotWave] Rename `stream` method to `acquire`. `stream` method is still an alias but deprecated and will be removed in the future

### 6.7.3 Fixed

- [linwave] Wait for all stream connection before `start_acquisition`

## 6.8 0.3.0 - 2021-06-15

### 6.8.1 Added

- [linwave] Multi-channel example
- [linwave] Optional `start` argument (timestamp) for `stream`
- [spotWave] Add examples
- [spotWave] Add firmware check

### 6.8.2 Changed

- [linwave] Channel arguments for `set_range`, `set_decimation` and `set_filter`
- [spotWave] `set_status_interval` with seconds instead of milliseconds
- [spotWave] Require firmware >= 00.25

### 6.8.3 Removed

- [linwave] Properties `input_range`, `decimation`, `filter_settings`

### 6.8.4 Fixed

- [linwave] ADC to volts conversion factor
- [spotWave] Aggregate TR/AE records to prevent IO timeouts

## 6.9 0.2.0 - 2020-12-18

First public release

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SEVEN**

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